



# Chapter Three: Mapping Earth

- **3.1 Position, Coordinates, and Maps**
- **3.2 Topographic Maps**
- **3.3 Bathymetric Maps**



## Section 3.1 Learning Goals

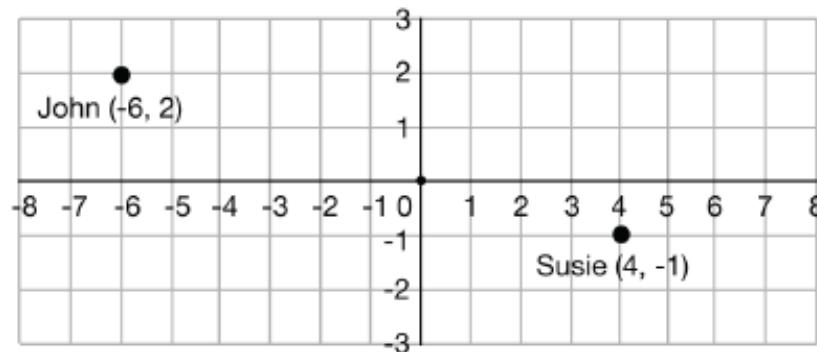
- **Describe an object's position relative to a reference point.**
- **Distinguish between lines of longitude and latitude.**
- **Analyze a map to determine scale, direction, and specific location.**

## Investigation 3A

### Positive and Negative Position

- **Key Question:**

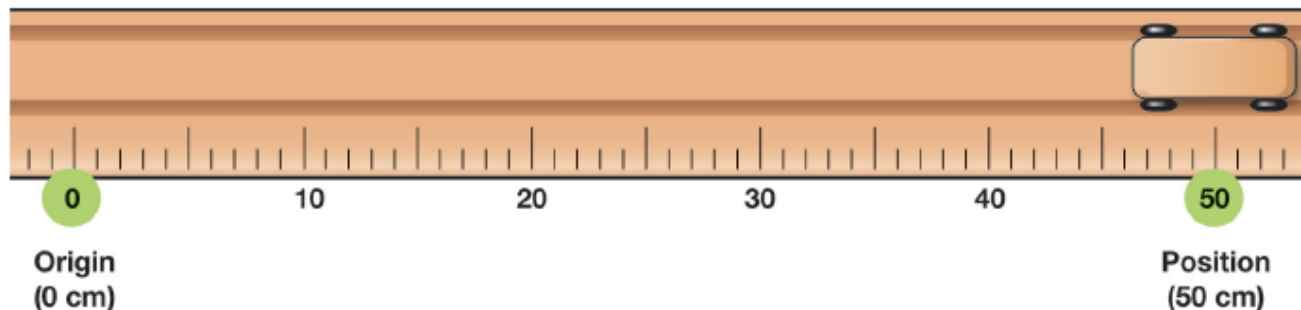
*How do we measure position in two dimensions?*





## 3.1 The position variable

- Motion is about knowing where things are and how they move.
- To understand where things are, we need to understand *position*.

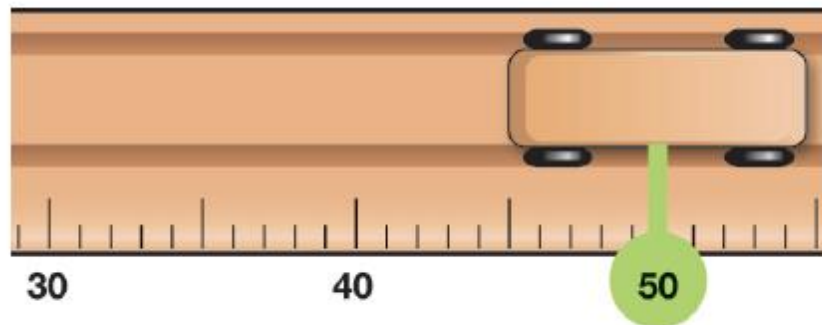




## 3.1 The position variable

- Position is a variable and it is always relative to an *origin*, or the place where the object's starting point was zero.

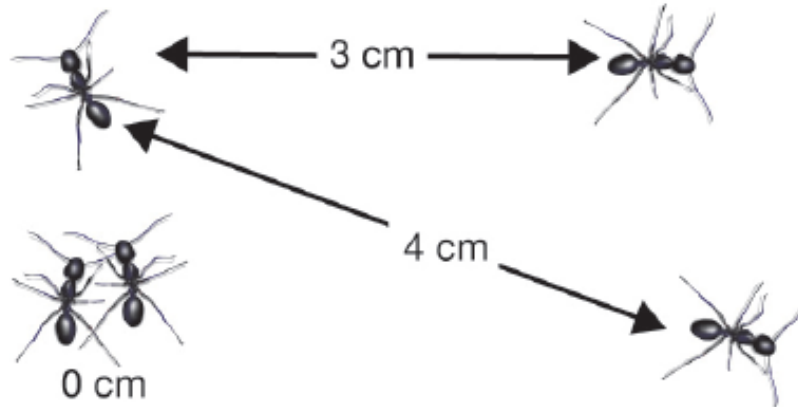
Where is the car if  
it moves 20 cm to the left?





## 3.1 Forward and backward

Distance is always positive or zero.



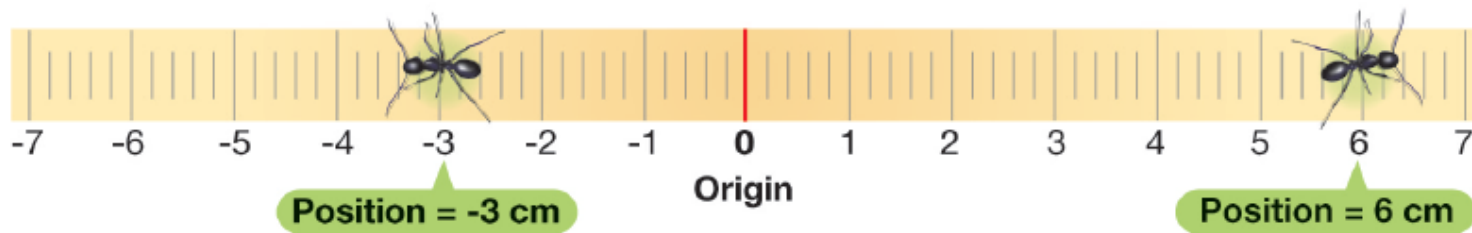
- **Position and distance are similar but not the same.**
- **Both use units of length.**
- **Distance can be zero or have positive values.**



## 3.1 Forward and backward

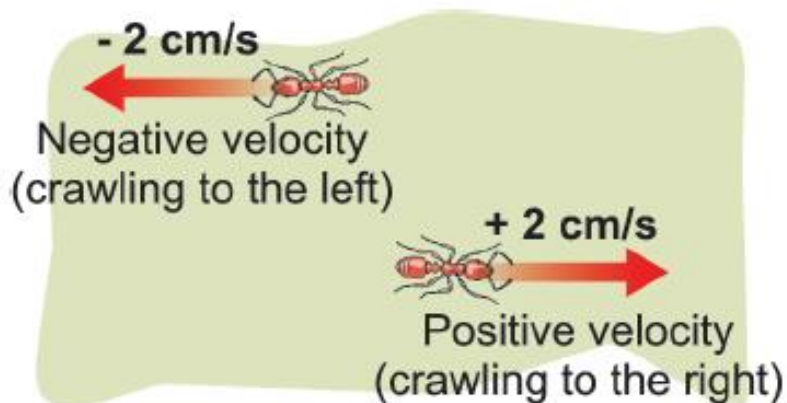
- Position uses positive and negative numbers.
- Positive numbers are for positions to the right (in front) of the origin.
- Negative numbers are for positions to the left (or behind) the origin.

Position can be positive or negative.



## 3.1 Vectors

- Position is an example of a kind of variable called a *vector*.
- A vector is a variable that tells you a direction as well as an amount.



Velocity is an example of a vector quantity. It includes both speed and direction.





## 3.1 Keeping track of where you are

- **Sojourner is a small robotic rover sent to explore Mars on the Pathfinder mission.**



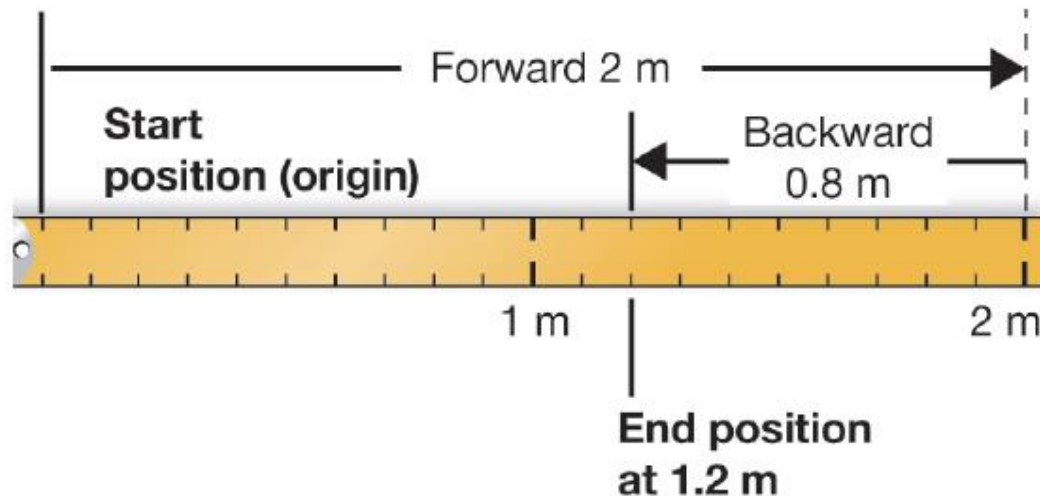
- **Sojourner explores ancient floodplains of Mars.**

**Where is Sojourner now?**



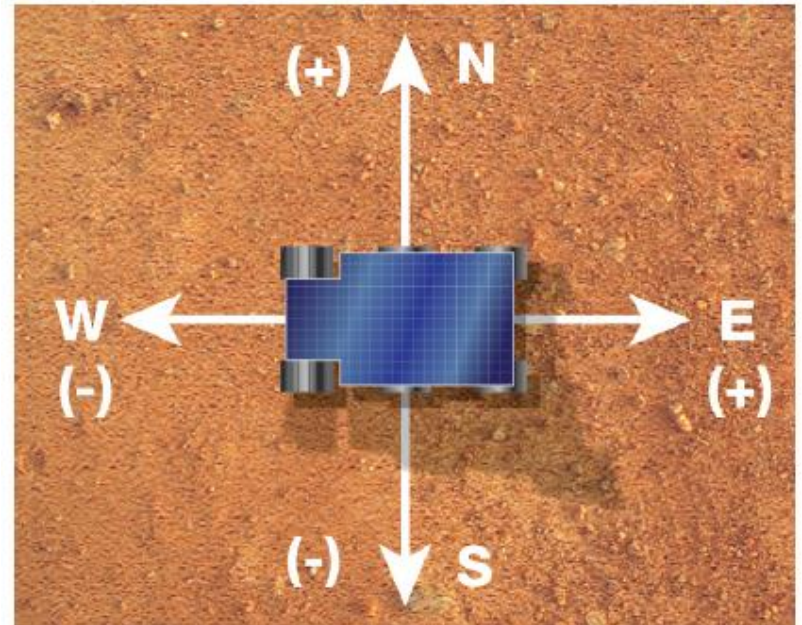
## 3.1 Keeping track of where you are

- As it moved, *Sojourner* needed to keep track of its position.
- The robot used speed and time data to calculate the position vector, and then added up position vectors to come up with a final position.



## 3.1 Maps and coordinates

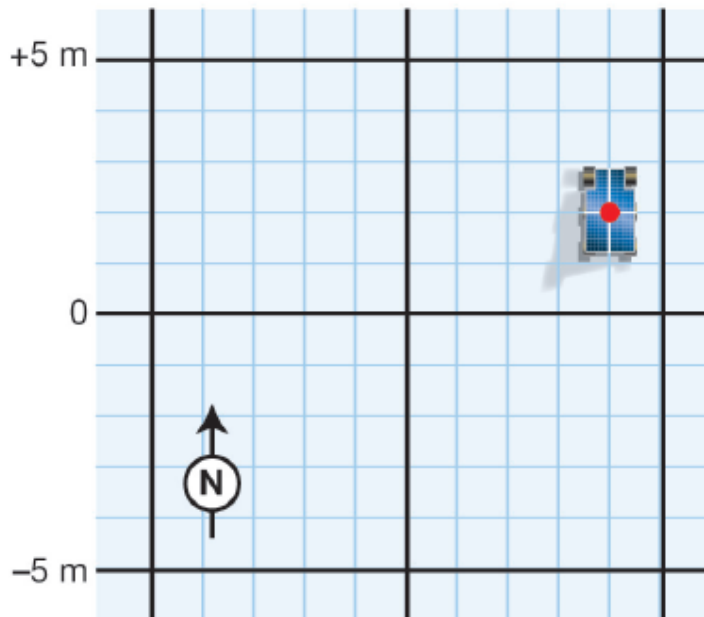
- If Sojourner was crawling on a straight board, it would have only two choices for direction, forward and reverse.
- Out on the surface of Mars, Sojourner has more choices. The possible directions include north, east, south, and west, and anything in between.





## 3.1 Maps and coordinates

- Sojourner's exact position can be described with two numbers.
- These numbers are called *coordinates*.



- This graph shows Sojourner at coordinates  $(+4, +2)$  m.

## 3.1 Maps and coordinates

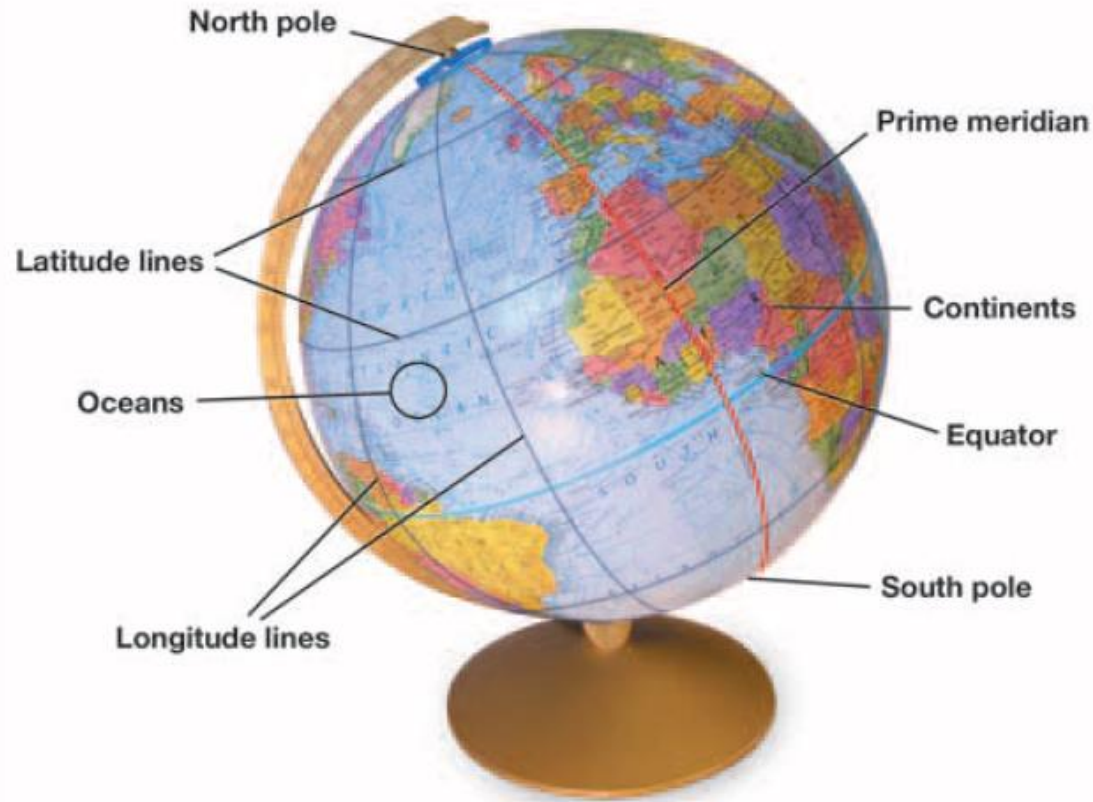
- A graph can also show any path Sojourner takes, curved or straight.

- This kind of graph is called a *map*.
- Street maps often use letters and numbers for coordinates.





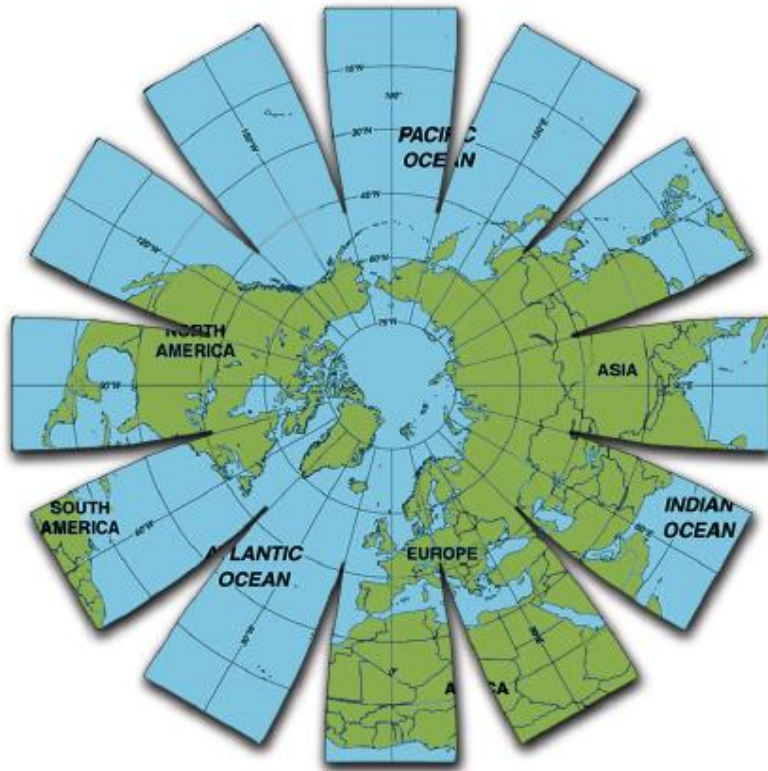
## 3.1 Globe



- **A *globe* is a model of Earth.**



## 3.1 Making globes

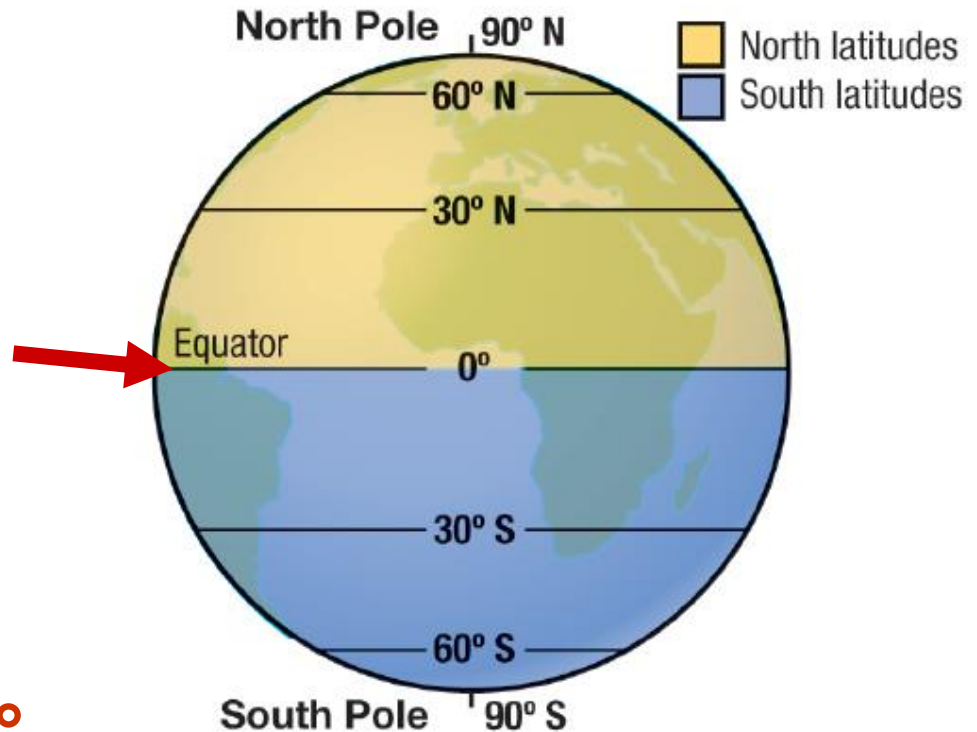


- You can cut a flat paper map to form it into a hemisphere for a globe.



## 3.1 The equator

- The *equator* is an imaginary line around Earth's middle that lies between the north and south poles.
- The equator is at  $0^\circ$  latitude.





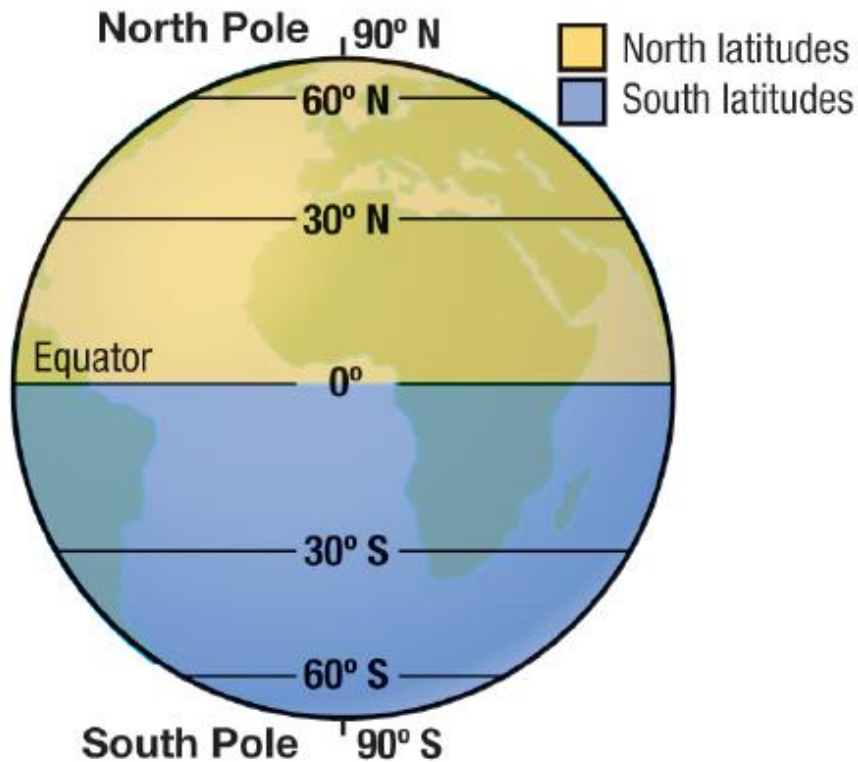
## 3.1 Latitude

- ***Latitude lines* are the horizontal lines on a map.**
- **They are lines that run east to west above and below the equator.**
- **Some latitude lines have special names.**

Name of Latitude Line	Approximate Location
Arctic Circle	66.5° N
Tropic of Cancer	23.5° N
Tropic of Capricorn	23.5° S
Antarctic Circle	66.5° S



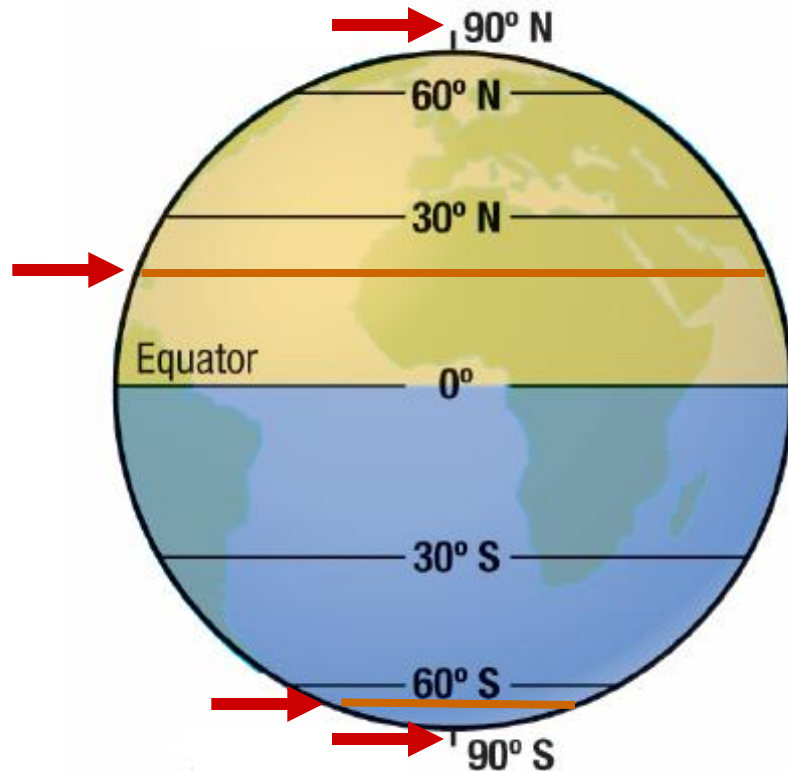
## 3.1 Latitude



- **Each line of latitude represents one degree on Earth's surface.**
- **Each degree is divided into 60 minutes and each minute is divided into 60 seconds.**



## 3.1 Latitude

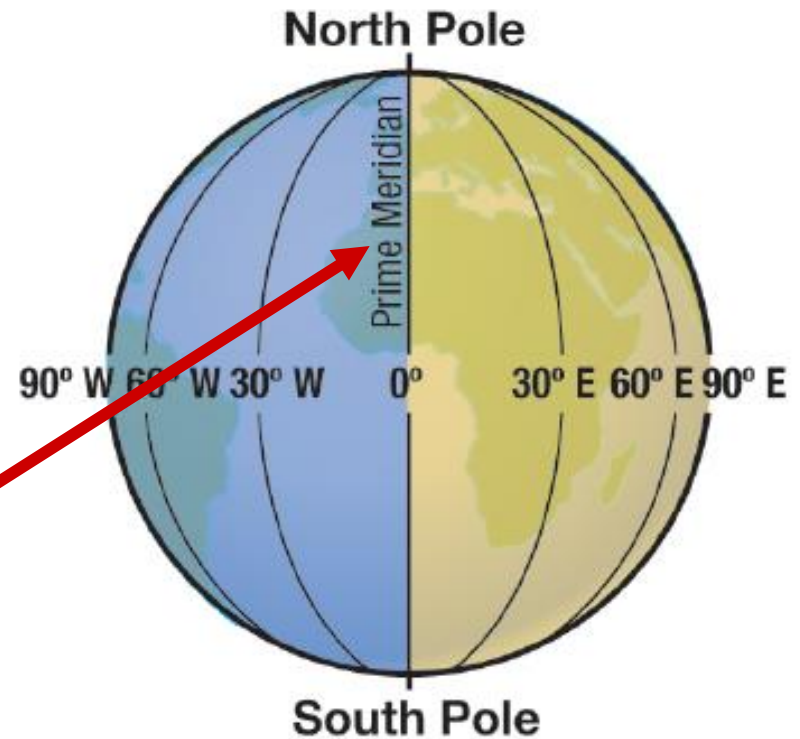


- **Minutes and seconds on maps represent distances, not time!**

**Can you name of these globe positions?**

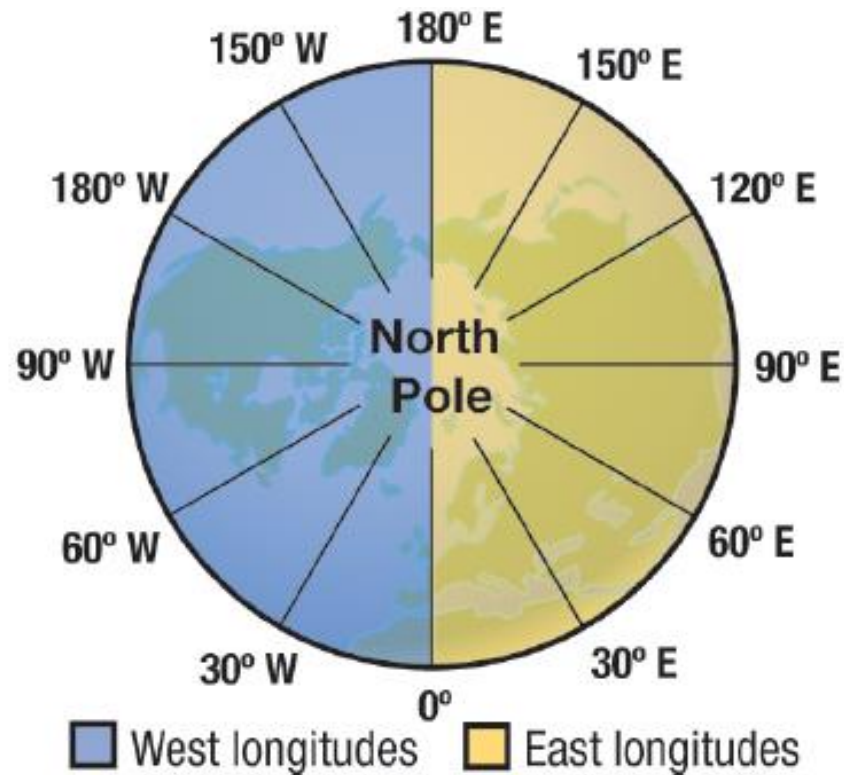
## 3.1 Longitude

- **Longitude lines (or meridians)** run north to south on a globe.
- The **prime meridian**, is an imaginary line that goes through Greenwich, England.
- The prime meridian is the **0°** line of longitude.



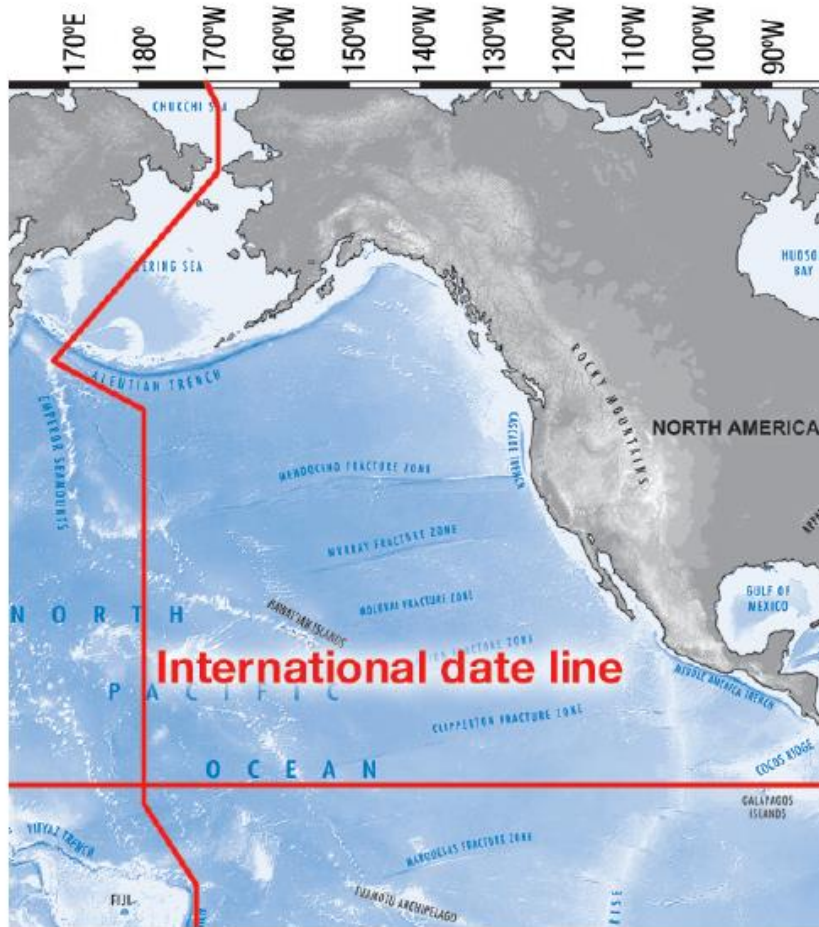


## 3.1 Longitude



- Longitude lines meet at the poles.

## 3.1 Longitude

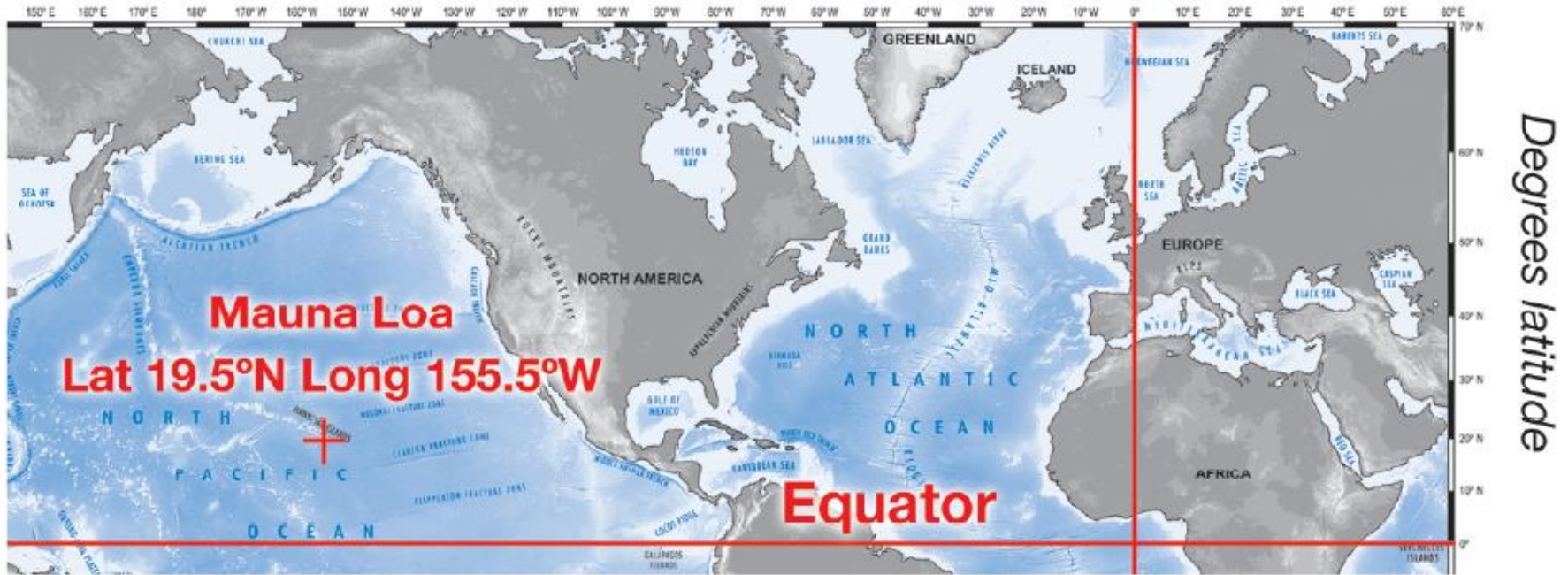


- The *international dateline* is an imaginary longitude line located mainly at 180°.
- For every 15° of longitude past the international dateline, time changes by one hour.



# Latitude and Longitude

Degrees longitude **Prime Meridian**



## 3.1 Projections

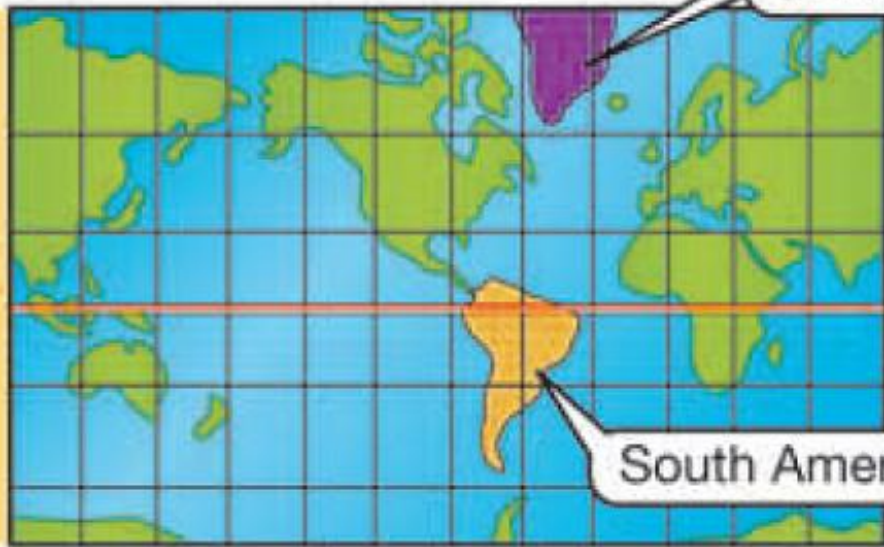
- Imagine trying to flatten a globe to make a map for traveling.
- A *Mercator projection* converts the center (most useful) section of the globe.
- Near the poles, the landforms are distorted on a flat map.
- Greenland and Antarctica appear much larger on maps than on globes.





# 3.1 Projections

**Mercator Projection**  
Converting a 3-D map to a 2-D map



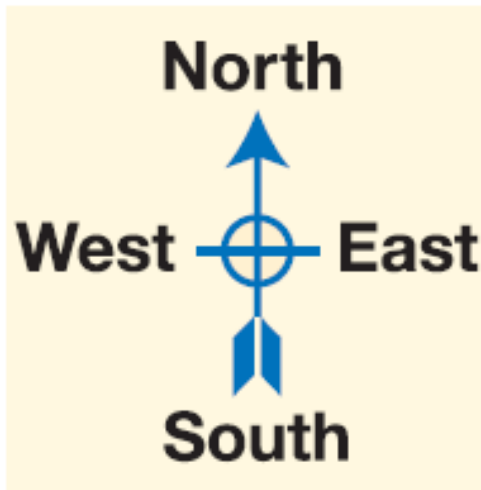
Greenland

South America



## 3.1 Features of maps

- On maps, there is usually a symbol that indicates *direction*—north, south, east, and west.










## 3.1 Features of maps

- Maps usually have a *legend* that lists and explains the symbols that are used on the map.

**Map Legend**

Topographic contour	
Campground	
Railroad track	
School	
Many buildings	



## 3.1 Features of maps

- Here are three kinds of map scales.

### Types of map scales

**Fractional**  
1/100,000

**Verbal**  
1 cm = 1 km



Can you suggest a use for each type of scale?



## 3.1 Features of maps

- A legend on a road map might include special lines to indicate different kinds of roads or the locations of parks, airports, and hospitals.

Can you locate all of the features of this map?

